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<u>L27</u> 125 and L26	14	<u>L27</u>
<u>L26</u> (399/21,22)[CCLS]	325	<u>L26</u>
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<u>L25</u> near7 (jam\$6 or troubl\$4) near12 (reach\$4 or predetermined or threshold or match\$4)	191	<u>L25</u>
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<u>L24</u> 13 and 110	0	<u>L24</u>
<u>L23</u> 13 and 19	0	<u>L23</u>
<u>L22</u> 13 and 18	0	<u>L22</u>
<u>L21</u> 13 and 17	0	<u>L21</u>
<u>L20</u> 13 and 16	5	<u>L20</u>

<u>L19</u> 13 and 15	8	<u>L19</u>
<u>L18</u> 13 and 14	8	<u>L18</u>
<u>L17</u> 12 and 110	0	<u>L17</u>
<u>L16</u> 12 and 19	0	<u>L16</u>
<u>L15</u> 12 and 18	3	<u>L15</u>
<u>L14</u> 12 and 17	0	<u>L14</u>
<u>L13</u> 12 and 16	6	<u>L13</u>
<u>L12</u> 12 and 15	16	<u>L12</u>
<u>L11</u> 12 and 14	16	<u>L11</u>
<u>L10</u> (712/29,225,248)[CCLS]	933	<u>L10</u>
<u>L9</u> (712/29-39)[CCLS]	1768	<u>L9</u>
<u>L8</u> (712/2-300)[CCLS]	12866	<u>L8</u>
<u>L7</u> (709/211,232)![CCLS]	1615	<u>L7</u>
<u>L6</u> (709/211-232)![CCLS]	33081	<u>L6</u>
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<u>L2</u> (print\$3 or cop\$4 or scann\$5 or writ\$4) near12 (imag\$3) and (track\$5 or count\$5) near7 (jam\$6 or troubl\$4) near12 (reach\$4 or predetermined or threshold or match\$4)	115	<u>L2</u>
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» Key

IEEE JNL IEEE Journal or Magazine

IEEE JNL IEE Journal or Magazine

IEEE CNF IEEE Conference Proceeding

IEEE CNF IEE Conference Proceeding

IEEE STD IEEE Standard

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[Position Location and Navigation Symposium, 2002 IEEE](#)
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- ☐ 5. **The projectile GRAM SAASM for ERGM and Excalibur**
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[Radar 97 \(Conf. Publ. No. 449\)](#)

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